## Key Stage 5 (12 \& 13)

| Course title: AS and A-Level Further Mathematics |  |  |
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| Exam board: OCR |  |  |
| Specification code: H235 (AS) and H245 |  |  |
| Autumn 1 <br> (September- <br> October) <br> Autumn 2 <br> (October- <br> December) <br> Spring 1 <br> (January- <br> February) | Teacher 1 | Teacher 2 |
|  | Pure Core 1: | Additional Pure Year 1: |
|  | Matrices | Number bases |
|  | - Language of matrices | - Notation |
|  | - Matrix operations | - Convert between base n and 10 |
|  | - Determinants of matrices | - Calculations |
|  | - Inverse matrices | - Proof |
|  | Complex Numbers | Divisibility |
|  | - Language of complex numbers | - Notation |
|  | - Express in cartesian form | - Standard divisibility tests |
|  | - Operations on complex numbers | - Division algorithm |
|  | - Argand diagrams | - Euclid's Lemma |
|  | - Loci | - Proof |
|  |  | - Modular arithmetic |
|  | Vectors |  |
|  | - Intersection of two lines | Prime Numbers |
|  | - Scalar product | - Fundamental theorem of arithmetic |
|  | - Vector product | - Integer combinations |
|  | Proof by Induction | Binary Operations |
|  |  | - Definitions |
|  | Roots of Polynomials | - Cayley tables |
|  | - Use relationships between symmetric functions | - Properties |



|  |  | - Fibonacci and Lucas numbers <br> - Proof by induction and sequences <br> - Solving recurrence systems <br> - Modelling |
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| Spring 2 <br> (February- <br>  <br> Summer 1 <br> (April-May) | Mechanics Year 1: <br> Work, Energy and Power <br> - Work done by a force <br> - Kinetic energy <br> - Potential, mechanical and conservation of energy <br> - Work done by a force at an angle <br> - Power |  |
|  | Dimensional Analysis <br> - Defining and calculating <br> - Units and dimensions of sums, differences and angles <br> - Finding dimensions and predicting formulae |  |
|  | Momentum and Collisions <br> - Momentum and impulse <br> - Collisions and conservation of momentum <br> - Restitution, kinetic energy and impulsive tension |  |
|  | Circular Motion <br> - Linear speed vs angular speed <br> - Acceleration in horizontal circular motion <br> - Problem solving |  |
| May/ June - AS Further maths exams |  |  |
| Summer 2 <br> (May-July), | Pure Core 2: <br> Series and Induction <br> - Review proof by induction | Mechanics Year 2: <br> Centres of Mass <br> - Of a system of pointed masses |


| Autumn 1 <br> (September- <br> October), <br> Autumn 2 <br> (October- <br> December), <br> Spring 1 <br> (January- <br> February), <br> Spring 2 <br> (February- <br> March) | - Summation and induction <br> - Standard summation series <br> - Method of differences <br> Lines and Planes in Space <br> - Equation of a plane <br> - Intersection between a line and a plane <br> - Angles between lines and planes <br> - Distances between points, lines and planes <br> Simultaneous Equations and Planes <br> - Linear simultaneous equations <br> - Intersections of planes <br> Powers and Roots of Complex Numbers <br> - De Moivre's Theorem <br> - Complex exponents <br> - Roots of complex numbers <br> - Roots of unity <br> - Further factorising <br> - Geometry of complex numbers <br> Complex Numbers and Trigonometry <br> - Deriving multiple angle formulae <br> - Application to polynomial equations <br> - Powers of trigonometric functions <br> - Trigonometric series <br> Hyperbolic Functions <br> - Defining hyperbolic functions | - Of standard shapes <br> - Of composite bodies <br> Work, Energy and Power <br> - Work done by a variable force <br> - Hooke's law <br> - Problem solving <br> Linear Motion Under a Variable Force <br> - Working with acceleration, velocity and displacement <br> - Variable force <br> Momentum and Collisions <br> - Variable force and vector notation <br> - Oblique impacts <br> - Oblique collisions <br> Circular Motion <br> - Conservation of mechanical energy <br> - Components of acceleration <br> - Problem solving <br> Centres of Mass <br> - By integration <br> - Equilibrium of a rigid body <br> Additional Pure Year 2: <br> Sequences and Series <br> - Solve second order recurrence relations |
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- Inverse hyperbolic functions
- Hyperbolic identities
- Solving harder hyperbolic equations
- Differentiation
- Integration


## Further Calculus Techniques

- Differentiation of inverse trigonometric functions
- Differentiation of inverse hyperbolic functions
- Using inverse trigonometric and hyperbolic functions in integration
- Using partial fractions in integration


## Applications of Calculus

- Maclaurin series
- Using standard Maclaurin series
- Improper integrals
- Volumes of revolution
- Mean value of a function


## Polar Coordinates

- Curves in polar coordinates
- Features of polar curves
- Changing between polar and Cartesian coordinates
- Area enclosed by a polar curve
- Area between two curves


## Differential Equations

- Terminology
- Integrating factor method


## Number Theory

- Solve simultaneous linear congruences
- Quadratic residues
- Fermat's little theorem


## Groups

- Lagrange's theorem for subgroups
- Isomorphic groups
- Groups of order greater than 7


## Further Vectors

- Volumes of tetrahedra and parallelopipeds
- The scalar triple product


## Surfaces and Partial Differentiation

- Classifying stationary points in 3-D
- Equation of a tangent plane of a 3-D curve


## Further Calculus

- Integration by reduction
- Arc lengths and surfaces of revolution

|  | - Homogeneous second order linear differential equations <br> - Non-homogeneous second order linear differential equations <br> Applications of Differential Equations <br> - Forming differential equations <br> - Simple harmonic motion <br> - Damping and damped oscillations <br> - Linear systems |  |
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| Summer 1 (April-May) | Revision | Revision |

